



LS-DYNA User-Defined Internal Ballistic Modeling

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Executive Summary



- LS-DYNA Explicit Finite Element Analysis software and CADPROG Internal Ballistic Analysis code are integrated as a single modeling tool to analyze pyro-mechanical devices.
- Coupling these two codes allows the ballistic calculations to be performed without modeling the propellant in an FEA mesh. At each LS-DYNA time step, CADPROG is run analytically using the kinematic data (stroke, velocity, chamber volume) fed back from the LS-DYNA simulation. The calculated pressure is then applied to a piston or any applicable surface mesh in LS-DYNA model interactively.
- All external loads such as friction, damping loads, assisting/resisting loads, locking/unlocking loads are modeled in LS-DYNA and coupled with pressure loads from CADPROG to create a fully defined equation of motion
- Both codes are written in Fortran 77. CADPROG is integrated in the LS-DYNA source code as a user-defined subroutine and recompiled to generate a custom executable.



LS-DYNA Overview



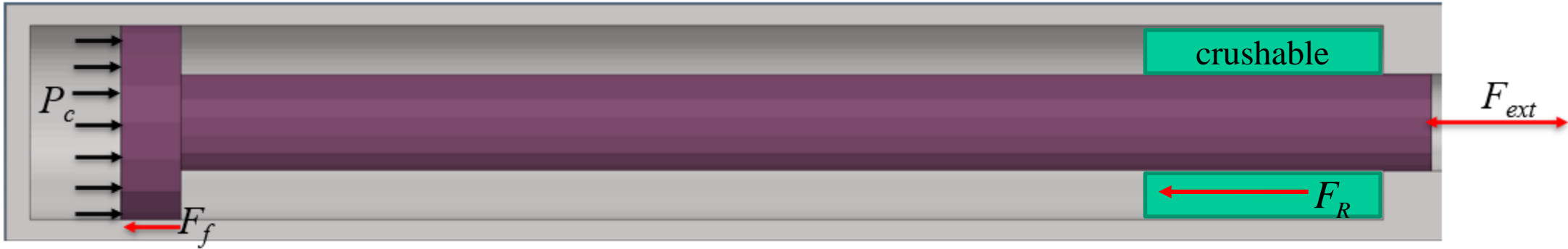
- Developed by Livermore Software Technology Corp (LSTC), LS-DYNA is a physics-based explicit FEA code that uses time integration to solve short duration transient and highly nonlinear dynamic problems
 - Extensive material model and Equation-of-State library, highly accurate contact algorithm and ability for Fluid-Structure Interaction (FSI) make LS-DYNA an excellent tool for evaluating complex mechanical and structural systems.
- Widely used for detonation problems using built-in JWL equation of state.
- While modeling the deflagration of a solid propellant with LS-DYNA is possible, it is very limited and mostly applicable to airbag systems that use gaseous nitrogen generated by burning of sodium azide.
- Allows users to define their own custom material models, equations of state and loading models through user-defined subroutines.



CADPROG Overview



- CADPROG is a one-dimensional internal ballistic code developed by NSWC Indian Head Division and is widely used to analyze CAD/PAD devices and ejection seat catapults
 - Differential Equations of State and Energy are solved using 4th Order Runge-Kutta Method
- Capable of modeling solid propellants with many geometries, such as multi-perforated cylindrical grains, spherical ball powders, flakes, slabs.
- Single and Hi-Lo dual chamber CAD/PAD devices can be modeled with a mixture of up to three propellant types.
- NASA/JSC made various updates to the source code over the years to improve its capabilities:
 - *Improved heat-loss module for during and post-burnout heat loss*
 - *Added stroke-dependent external load capability*



- Conservation of Energy

$$c_v \frac{d(m_p T)}{dt} = c_v T_0 \frac{dm_p}{dt} - A_p P_c \frac{dx}{dt} - \frac{d(E_{HL})}{dt}$$

- Noble-Abel Equation of State

$$P_c [V_c + A_p x - \frac{C - m_p}{\rho} - \eta m_p] = m_p F \frac{T}{T_0}$$

- Equation of Motion

$$m \frac{d^2 x}{dt^2} = P_c A_p - F_f - F_R - F_{ext}$$

- Conservation of Mass

$$\frac{dm_p}{dt} = \rho \cdot S \cdot r$$

- Propellant Burn Rate

$$r = B P_c^n$$

With LS-DYNA/CADPROG feedback method, Acceleration is calculated by LS-DYNA using the CADPROG pressure and LS-DYNA Modeled Loads (friction, crush resistance, external aero, etc.)



Creating LS-DYNA User-Defined Executable



- Fortran source code that contains a collection of subroutines is required to create a custom LS-DYNA executable.
 - The Fortran file `dyn21.f` can be obtained from LSTC.
 - `dyn21.f` is modified by the user to integrate the user-defined loading, in this case the entire CADPROG code.
 - `dyn21.f` must be compiled by using the latest version of Intel® Visual Fortran Compiler.
 - Running the *makefile* supplied by LSTC compiles the file and links with the object files that are also provided.
 - The new LSDYNA.EXE file should be selected as the solver when running LS-DYNA.
 - Subroutine receives TIME, TIMESTEP, elemental X and V input and initial conditions from the LS-DYNA run, and outputs calculated pressure curve, $udL(i)$, interactively for each element “i” on selected pressure surface.



User-Defined Loading Keyword Commands



- User-defined loading is invoked in LS-DYNA keyword file (input deck) with following keyword commands:

*USER_LOADING_SET

| Card 1 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
|----------|-----|-------|------|-----|-----|-----|-----|-------|
| Variable | SID | LTYPE | LCID | CID | SF1 | SF2 | SF3 | IDULS |

ELEMENT SET id Load Type "PRESSSS"

*USER_LOADING

| Card 1... | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
|-----------|--------|--------|--------|--------|--------|--------|--------|--------|
| Variable | PARAM1 | PARAM2 | PARAM3 | PARAM4 | PARAM5 | PARAM6 | PARAM7 | PARAM8 |

PARAMi : CADPROG input parameters



User-Defined Mods to dyna21.f



```

subroutine loadsetud(time,lft,llt,crv,iduls,parm,nod,nnml)
# 803
c
c*****
c| Livermore Software Technology Corporation (LSTC) |
c| ----- |
c| Copyright 1987-2008 Livermore Software Tech. Corp |
c| All rights reserved |
c*****
c
c Input (not modifiable)
c time : analysis time
c x : coordinate of node or element center
c d : displacement of node or element center
c v : velocity of node or element center
c temp : temperature of node or element center
c crv : value of LCURV at time=time
c iduls: id of user_loading_set
c parm : parameters from user_loading
c nod : internal node numbers
c nnml : offset for node block
c Output (defined by user)
c udl : user-defined load curve value
include 'nlqparm'
common/aux8loc/
x1(nlq),x2(nlq),x3(nlq),v1(nlq),
v2(nlq),v3(nlq),d1(nlq),d2(nlq),
d3(nlq),temp(nlq),udl(nlq),
xx11(nlq),xx21(nlq),xx31(nlq),
xx12(nlq),xx22(nlq),xx32(nlq),
xx13(nlq),xx23(nlq),xx33(nlq),
xx14(nlq),xx24(nlq),xx34(nlq),
xctr(nlq),yctr(nlq),zctr(nlq),
f(nlq),tr1(nlq),tr2(nlq),tr3(nlq)
c
c
c
c S.OGUZ 5/17/2023
c
dimension parm(*),nod(*)
common/bk02/iburn,dt1,dt2,isdo
COMMON /RUNDAT/ XX(8),OLDX(8),FF(8),X,P,T,C,V,ACCEL,
+ PL,PLA,TH,TL,CH,CL,FC
open(16, file='UD_load.out')

```

```

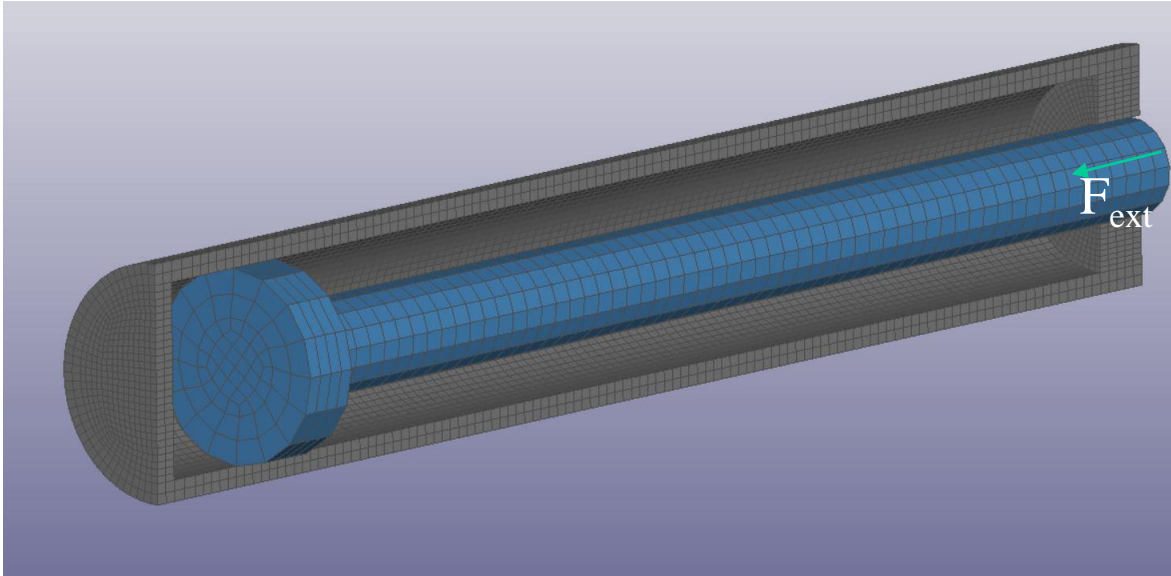
c
c input to CADPROG: DT1,TIME, D1(I),V1(I)
c return from CADPROG: PRESSURE
C***** CADPROG PARAMETERS *****
C Fixed input parameters are read from CAGDROG subroutine
C*****
call CADPROG(parm)
x=d1(1)
V=v1(1)
c
c CALL SUBROUTINE RUN TO to start Runge-Kutta runs
c
call RUN(DT1,TIME, ddd, vvv)
c
c Assign calculated pressure to each element in the pressure segment set
c Segment set is defined in *USER_LOADING_SET in keyword file
c
do i=lft,llt
udL(i)= P ! P is the calculated pressure in CADPROG
enddo
c
c write a tabulated list of CADPROG results
c
write(16,106) TIME,P,X,V,FC
106 format(1X,F10.7,2X,F8.1,2X,F8.3,2X,F8.2, 2X,F9.3)
continue
return
end
c
subroutine cadprog(parm)
.
.....enter cadprog fixed parameters here
.
.
end
return
c
subroutine RUN(DT,TIME, ddd, vvv)
.
....enter Runge-Kutta and all other CADPROG subroutines here
.
.
end
return

```

Pressure on each element

Output for plotting

CADPROG Subroutines



- Flexible Housing and Rigid Piston
- Piston pushes a 190 lbs mass
- FEA Model contains 26,256 solid elements
- Housing constrained at one end
- 10 inches of stroke

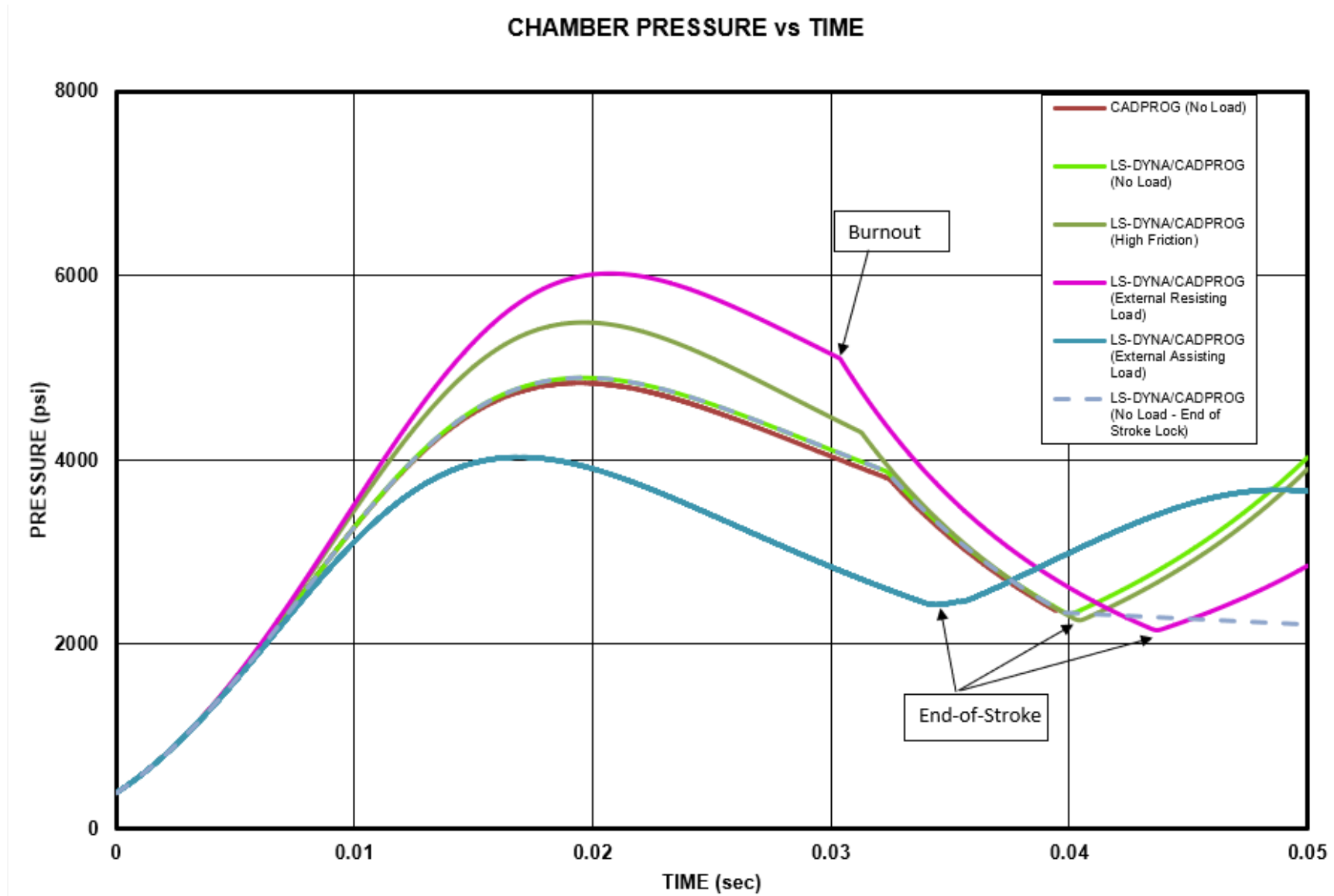
- *Propellant*: 7-perforated HES5808 grains
- *Igniter*: BKNO_3

- Contact with static and dynamic friction coeff.
*CONTACT_SURFACE_TO_SURFACE

- Various external assisting and resisting loads applied to piston end as nodal force.

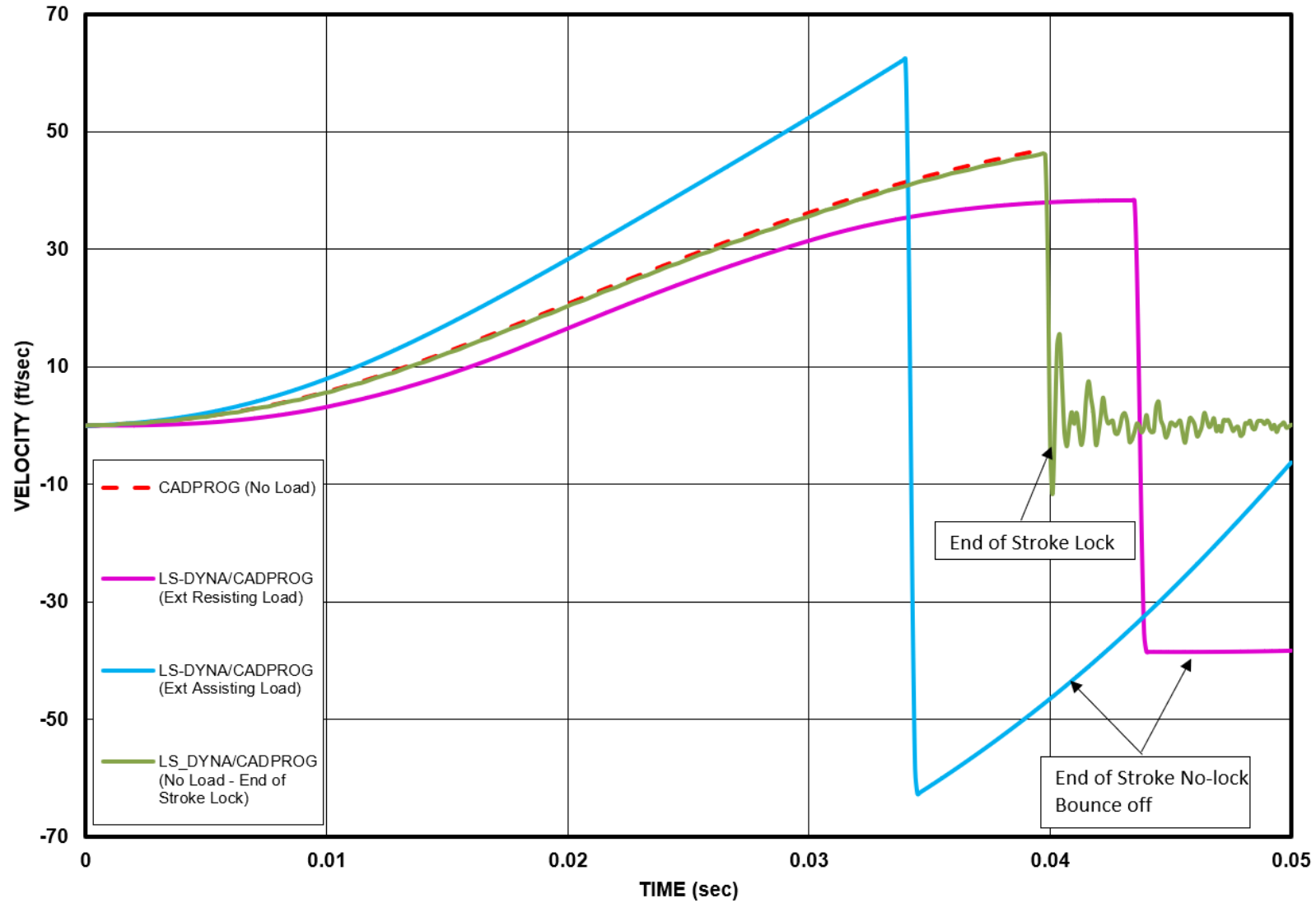


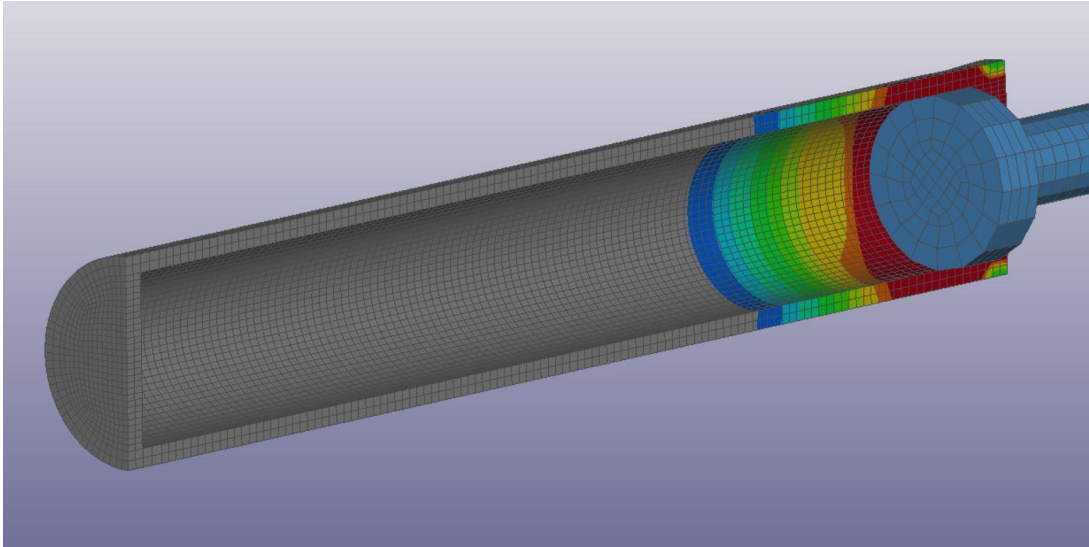
Pressure Results for various load conditions



Piston Velocity

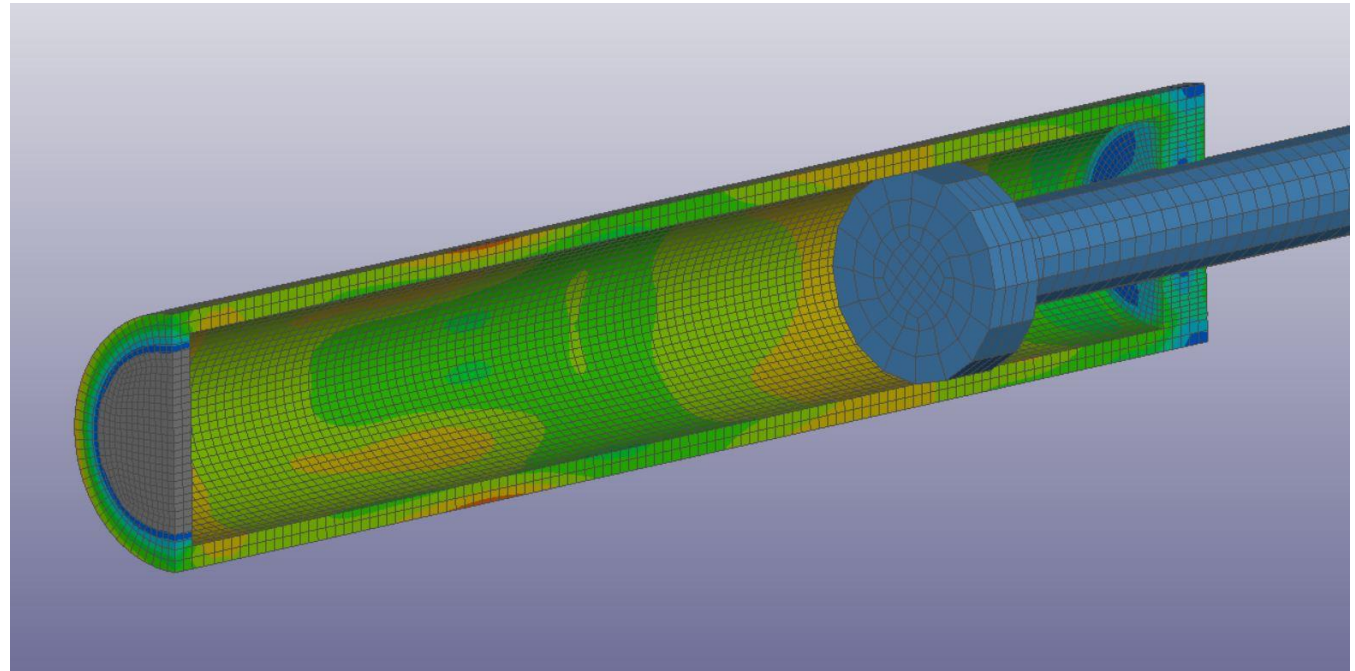
VELOCITY vs TIME





End-of-Stroke Impact

Post impact bounce off





Future Work



- In our current model, pressure is applied only on pre-selected mesh surfaces such as the piston area and initial volume walls.
- Adding capability to update pressure application mesh surface (inner walls of gas chamber) as the volume expands will allow full structural analysis (stress, strain) in real time.
 - Euler mesh inside chamber volume with user-defined CADPROG EOS could be an option
- Hi-Lo chamber ballistic capability can be added to model the gas flow from high-pressure chamber to low-pressure chamber by using unique LS-DYNA solvers such as ICFD for incompressible and CESE for compressible flows.



Questions?



References



- [1] Oguz, S and Salazar, F, “Orion Parachute Riser Cutter Development”, 47th AIAA Joint Propulsion Conference, San Diego, CA, August 1-3, 2011.
- [2] LS-DYNA Keyword User’s Manual, Version R13, Livermore Software Technology Corporation.
- [3] Holter, W.H., *Simplified Solutions to the Interior Ballistic Problems of Cartridge Actuated Devices*, U.S. Naval Weapons Laboratory, Report No. 1752, May 1962.
- [4] Adoum, M., “Examples Manual for *USER_LOADING Option”, 4th European LS-DYNA Users Conference



Nomenclature



A_p =piston area

B =burn rate coefficient

C =propellant mass

c_v =specific heat at constant volume

E_{HL} =heat loss

F =impetus

F_{EXT} =external force

F_f =friction force

m =imparted mass

m_p =mass of propellant gas produced

n =burn rate exponent

P_C =chamber pressure

r =propellant burn rate

S =propellant surface area

T =gas temperature

T_o =isochoric flame temperature

V_C =initial chamber volume

x =stroke

V =velocity

ρ =propellant mass density

η =co-volume

CAD/PAD = Cartridge/Propellant Actuated Device

JWL = Johns-Wilkins-Lee Equation of State